### Variants of Canonical Correlation Analysis

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#### Canonical Correlation Analysis (Hotelling, 1936)

- Let (X, Y) ∈ ℝ<sup>p1</sup> × ℝ<sup>p2</sup> denote random vectors with covariances (Σ<sub>11</sub>, Σ<sub>22</sub>) and cross-covariance Σ<sub>12</sub>.
- CCA finds pairs of linear projections of the two views, (v'X, u'Y) that are maximally correlated:

$$(v^*, u^*) = \operatorname*{argmax}_{v,u} \operatorname{corr}(v'X, u'Y)$$
$$= \operatorname{argmax}_{v,u} \frac{v'\Sigma_{12}u}{\sqrt{v'\Sigma_{11}vu'\Sigma_{22}u}}$$
$$= \operatorname{argmax}_{v'\Sigma_{11}v=u'\Sigma_{22}u=1} v'\Sigma_{12}u$$

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• When finding multiple pairs of vectors  $(v^i, u^i)$ , subsequent projections are also constrained to be uncorrelated with previous ones:

$$v^i \Sigma_{11} v^j = u^i \Sigma_{22} u^j = 0 \text{ for } i < j.$$

• We obtain the following formulation to identify the top  $k \leq \min(p_1, p_2)$  projections:

maximize:  $\operatorname{tr}(V'\Sigma_{12}U)$ subject to:  $V'\Sigma_{11}V = U'\Sigma_{22}U = I.$ 

where  $V \in \mathbb{R}^{p_1 \times k}$  and  $U \in \mathbb{R}^{p_2 \times k}$ .

- Define  $T_1 \triangleq \Sigma_{11}^{-1} \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}$  and  $T_2 \triangleq \Sigma_{22}^{-1} \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12}$ .
- Then, the optimum objective value is the sum of the top k eigenvalues of  $T_1$  (or  $T_2$ ).
- Let  $V_k$  be the matrix of the first k eigenvectors of  $T_1$  and  $U_k$  be the matrix of the first k eigenvectors of  $T_2$ .

• Then, the optimum is attained at  $(V^*, U^*) = (V_k, U_k)$ .

# The Two-Block Mode B of Wold's Algorithm (Wold, 1975; Wegelin, 2000)

• Given the centered data  $\mathbf{X} \in \mathbb{R}^{n \times p_1}$  and  $\mathbf{Y} \in \mathbb{R}^{n \times p_2}$ ,

$$\hat{T}_1 = (\mathbf{X}'\mathbf{X})^{-1}(\mathbf{X}'\mathbf{Y})(\mathbf{Y}'\mathbf{Y})^{-1}(\mathbf{Y}'\mathbf{X}),$$
$$\hat{T}_2 = (\mathbf{Y}'\mathbf{Y})^{-1}(\mathbf{Y}'\mathbf{X})(\mathbf{X}'\mathbf{X})^{-1}(\mathbf{X}'\mathbf{Y}).$$

• We can obtain the eigenvectors and eigenvalues of  $\hat{T}_1$  and  $\hat{T}_2$  by power method.

• It can be viewed as an iterative projection procedure.

#### The Two-Block Mode B of Wold's Algorithm

• Let 
$$\omega = \mathbf{Y}u$$
 and  $\xi = \mathbf{X}v$ .

• Wold's Algorithm :

- $1 r \leftarrow 1$ .
- 2 Let  $\mathbf{X}^{(r)} \leftarrow \mathbf{X}$  and  $\mathbf{Y}^{(r)} \leftarrow \mathbf{Y}$ .
- 3 Standardize  $\mathbf{X}^{(r)}$  and  $\mathbf{Y}^{(r)}$ .
- 4 Set  $k \leftarrow 0$ .
- 5 Assign arbitrary normalized values  $\hat{v}_r^{(0)}$  and  $\hat{u}_r^{(0)}$ .
- 6 Estimate  $\xi_r, \omega_r, v_r$  and  $u_r$  iteratively, as follows: **Repeat** 
  - $\begin{array}{c} \bullet \quad k \leftarrow k+1. \\ \bullet \quad \hat{\xi}_r^k \leftarrow \mathbf{X}^{(r)} \hat{v}_r^{(k-1)} \text{ and } \hat{\omega}_r^k \leftarrow \mathbf{Y}^{(r)} \hat{u}_r^{(k-1)} \end{array}$

3 Compute  $\hat{v}_r^{(k)}$  and  $\hat{u}_r^{(k)}$  by performing multiple regression:

$$\begin{split} \hat{u}_{r}^{(k)} &= \ \operatorname*{argmin}_{u_{r}^{(k)}} | \hat{\xi}_{r}^{k} - \mathbf{Y}^{(r)} u_{r}^{(k)} |^{2} \\ \hat{v}_{r}^{(k)} &= \ \operatorname*{argmin}_{v_{r}^{(k)}} | \hat{\omega}_{r}^{k} - \mathbf{X}^{(r)} v_{r}^{(k)} |^{2} \\ \hat{v}_{r}^{(k)} &= \ \operatorname*{argmin}_{v_{r}^{(k)}} | \hat{\omega}_{r}^{k} - \mathbf{X}^{(r)} v_{r}^{(k)} |^{2} \end{split}$$

Normalize  $\hat{v}_r^{(k)}$  and  $\hat{u}_r^{(k)}$ .

#### The Two-Block Mode B of Wold's Algorithm

- Wold's algorithm(cont')
  - 7 Fit the simple linear regression :

$$\begin{aligned} \mathbf{X}_{j}^{(r)} &\approx \hat{\gamma}_{j}\hat{\xi}_{r}, \quad j=1,...,p_{1} \\ \mathbf{Y}_{j}^{(r)} &\approx \hat{\theta}_{j}\hat{\omega}_{r}, \quad j=1,...,p_{2} \end{aligned}$$

8 Determine the residual matrices of  $\mathbf{X}^{(r)}$  and  $\mathbf{Y}^{(r)}$ .

$$\begin{aligned} \mathbf{X}^{(r+1)} &\leftarrow \mathbf{X}^{(r)} - \hat{\xi}_r \hat{\gamma}' \\ \mathbf{Y}^{(r+1)} &\leftarrow \mathbf{Y}^{(r)} - \hat{\omega}_r \hat{\theta}' \end{aligned}$$

9  $r \leftarrow r + 1$  and return to Step 3.

## Penalized CCA(Waaijenborg et al., 2008)

- Penalized linear regression techniques can be easily adapted to Wold's algorithm, by modifying step 6-3.
- We used the elastic net.
- Selection of the penalty parameters : minimize  $\Delta_{cor}$ .

$$\Delta_{\rm cor} = \frac{\sum_{j=1}^{k} ||cor(\mathbf{X}_{-j}\hat{v}^{-j}, \mathbf{Y}_{-j}\hat{u}^{-j})| - |cor(\mathbf{X}_{j}\hat{v}^{-j}, \mathbf{Y}_{j}\hat{u}^{-j})||}{k}$$

# Sparse CCA via Precision Adjusted Iterative Thresholding (Chen et al., 2013)

- Waaijenborg(2008), Wiesel et al.(2008) :
  - based on heuristics to avoid the non-convex nature of CCA problem.
  - there is no guarantee whether these algorithms would lead to consistent estimators.
- Witten et al.(2009), Parkhomenko et al.(2009) :
  - using diagonal matrix or even identity matrix to approximate the unknown matrices  $(\Sigma_1^{-1}, \Sigma_2^{-1})$ .

#### Proposition 1.

When  $\Sigma_{12}$  is of rank 1, the solution (up to sign jointly) of CCA problem is  $(\theta, \eta)$  if and only if the covariance structure between X and Y can be written as

$$\Sigma_{12} = \lambda \Sigma_{11} \theta \eta^T \Sigma_{22}$$

where  $0 < \lambda \leq 1$ ,  $\theta^T \Sigma_{11} \theta = 1$  and  $\eta^T \Sigma_{22} \eta = 1$ . In other words, the correlation between  $a^T X$  and  $b^T Y$  are maximized by  $\operatorname{corr}(\theta^T X, \eta^T Y)$ , and  $\lambda$  is the canonical correlation between X and Y.

#### Proposition 2.

For general  $\Sigma_{12}$  with rank  $r \ge 1$ , the solution (up to sign jointly) of CCA problem is  $(\theta_1, \eta_1)$  if and only if the covariance structure between X and Y can be written as

$$\Sigma_{12} = \lambda \Sigma_{11} \bigg( \sum_{i=1}^r \lambda_i \theta_i \eta_i^T \bigg) \Sigma_{22}$$

where  $\lambda_1 > \lambda_2 > ... > \lambda_r > 0$ ,  $\theta_i^T \Sigma_{11} \theta_j = \mathbb{I}(i=j) = \eta_i^T \Sigma_{22} \eta_j$ .

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We propose a probabilistic model of (X, Y), so that the canonical directions (θ, η) are explicitly modeled in the joint distribution of (X, Y).

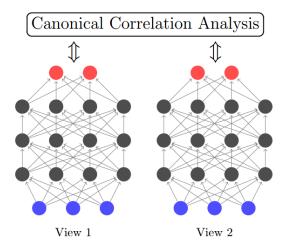
The Single Canonical Pair Model  $\begin{pmatrix} X \\ Y \end{pmatrix} \sim N\left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} \Sigma_{11} & \lambda \Sigma_{11} \theta \eta^T \Sigma_{22} \\ \lambda \Sigma_{22} \eta \theta^T \Sigma_{11} & \Sigma_{22} \end{pmatrix}\right)$ with  $\Sigma_{11} > 0, \Sigma_{22} > 0, \theta^T \Sigma_{11} \theta = \eta^T \Sigma_{22} \eta = 1$  and  $0 < \lambda \le 1$ .

#### Algorithm : CAPIT

**Input** : Sample covariance matrices  $\hat{\Sigma}_{12}$ ; Estimators of precision matrix  $\hat{\Omega}_{11}$ ,  $\hat{\Omega}_{22}$ ; Initialization pair  $\alpha^{(0)}$ ,  $\beta^{(0)}$ ; Thresholding level  $\gamma_1$ ,  $\gamma_2$ . **Output** : Canonical direction estimator  $\alpha^{(\infty)}$ ,  $\beta^{(\infty)}$ . Set  $\hat{A} = \hat{\Omega}_{11} \hat{\Sigma}_{12} \hat{\Omega}_{22}$ ; **repeat** 

- Right Multiplication:  $\omega^{l,(i)} = \hat{A}\beta^{(i-1)}$ ;
- Left Thresholding :  $\omega_{th}^{l,(i)} = T(\omega^{l,(i)}, \gamma_1);$
- Left Normalization :  $\alpha^{(i)} = \omega_{th}^{l,(i)} / \|\omega_{th}^{l,(i)}\|;$
- Left Multiplication :  $\omega^{r,(i)} = \alpha^{(i)} \hat{A};$
- Right Thresholding :  $\omega_{th}^{r,(i)} = T(\omega_{th}^{r,(i)}, \gamma_2);$
- Right Normalization :  $\beta^{(i)} = \omega_{th}^{r,(i)} / \|\omega_{th}^{r,(i)}\|$ ; until Convergence of  $\alpha^{(i)}$  and  $\beta^{(i)}$ .

# Deep Canonical Correlation Analysis (Andrew et al., 2013)



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• If  $\theta_1$  is the vector of all parameters of the first view, and similarly for  $\theta_2$ , then

$$(\theta_1^*, \theta_2^*) = \operatorname*{argmax}_{(\theta_1, \theta_2)} \operatorname{corr}(f(X; \theta_1), g(Y; \theta_2))$$

- $H \in \mathbb{R}^{n \times o}, K \in \mathbb{R}^{n \times o}$ : data matrices with top-level representation.
- $\overline{H}$ ,  $\overline{K}$ : centered data matrices.
- Define  $\hat{\Sigma}_{12} = \frac{1}{n-1} \bar{H}' \bar{K}$  and  $\hat{\Sigma}_{11} = \frac{1}{n-1} \bar{H}' \bar{H} + r_1 I$  (resp.  $\hat{\Sigma}_{22}$ ).
- If we take k = o, then

$$\operatorname{corr}(H, K) = ||T||_{tr} = \operatorname{tr}(T'T)^{1/2}$$

where 
$$T = \hat{\Sigma}_{11}^{-1/2} \hat{\Sigma}_{12} \hat{\Sigma}_{22}^{-1/2}$$
.

- Optimizing this quantity using gradient-based optimization.
- If the singular decomposition of T is T = UDV' then,

$$\frac{\partial \operatorname{corr}(H,K)}{\partial H} = \frac{1}{n-1} (2\Delta_{11}\bar{H} + \Delta_{12}\bar{K}).$$

where

$$\Delta_{12} = \hat{\Sigma}_{11}^{-1/2} U V' \hat{\Sigma}_{22}^{-1/2}$$

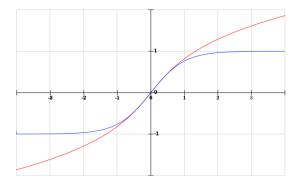
and

$$\Delta_{11} = -\frac{1}{2}\hat{\Sigma}_{11}^{-1/2}UDU'\hat{\Sigma}_{11}^{-1/2}$$

and  $\partial \operatorname{corr}(H, K) / \partial K$  has a symmetric expression.

- The correlation objective is a function of the entire training set that does not decompose into a sum over data points.
- Full-match optimization using the L-BFGS second-order optimization method.
- Pre-training : denoising autoencoder
- Non-linear function : a novel non-saturating sigmoid function based on the cube root.

If g : R → R is the function g(y) = y<sup>3</sup>/3 + y, then our function is s(x) = g<sup>-1</sup>(x).



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• *s* is not bounded, and its derivative falls off much more gradually with *x*.

- We hypothesize that these properties make *s* better-suited for batch optimization with second-order methods.
- The derivative of s is a simple function of its value.

• 
$$s'(x) = (s^2(x) + 1)^{-1}$$
.

• To compute s(x), we use Newton's method.