

Next Basket Recommendation

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Introduction : Next Basket Recommendation

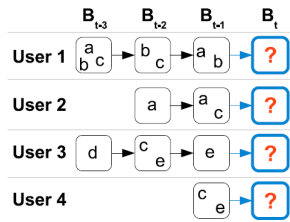


Figure 1: Sequential basket data with four users and five items

Which basket should be recommended to the user?

Properties :

- Special type of item recommendation (sets of items)
- Reoccurring items
- Possible scenario : online store

Factorizing Personalized Markov Chains for Next-Basket Recommendation

International World Wide Web Conference 2010

Steffen Rendel, Christoph Freudenthalen, Lars Schmidt-Thieme

Problem Formulation

- $U = \{u_1, \dots, u_{|U|}\}$: users
- $I = \{i_1, \dots, i_{|I|}\}$: items
- $\mathcal{B}^u = (B_1^u, \dots, B_{t_u-1}^u)$: historical baskets of user u with $B_t^u \subseteq I$
- $\mathcal{B} = \{\mathcal{B}^{u_1}, \dots, \mathcal{B}^{u_{|U|}}\}$: purchase history of all users

Markov Chains for Baskets

- A sequence of random variables X_1, X_2, \dots is a Markov chain of order m if

$$\begin{aligned} & p(X_t = x_t | X_{t-1} = x_{t-1}, \dots, X_1 = x_1) \\ &= p(X_t = x_t | X_{t-1} = x_{t-1}, \dots, X_{t-m} = x_{t-m}). \end{aligned}$$

- A personalized Markov chain of order $m = 1$ for basket problem is :

$$p(B_t^u | B_{t-1}^u).$$

Markov Chains for Baskets

- We model transitions over $|I|$ binary variables that describe a basket:

$$a_{I,i} := p(i \in B_t | I \in B_{t-1})$$

- Predictions using simplified Markov chains :

$$p(i \in B_t | B_{t-1}) := \frac{1}{|B_{t-1}|} \sum_{I \in B_{t-1}} p(i \in B_t | I \in B_{t-1})$$

Markov Chains for Baskets

- Maximum likelihood estimator for $a_{l,i}$ given \mathcal{B} is :

$$\begin{aligned}\hat{a}_{l,i} &= \hat{p}(i \in B_t | l \in B_{t-1}) = \frac{\hat{p}(i \in B_t \wedge l \in B_{t-1})}{\hat{p}(l \in B_t)} \\ &= \frac{|(B_t, B_{t-1}) : i \in B_t \wedge l \in B_{t-1}|}{|(B_t, B_{t-1}) : l \in B_{t-1}|}\end{aligned}$$

- Example :

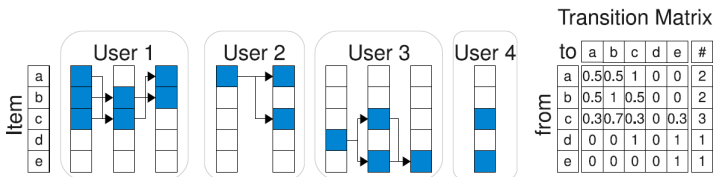


Figure 2: Non-personalized Markov chain

Personalized Markov Chains

- We represent each MC by the transitions over items, but now user-specific:

$$a_{u,l,i} := p(i \in B_t^u | l \in B_{t-1}^u)$$

- The prediction depends only on the users transitions:

$$p(i \in B_t^u | B_{t-1}^u) := \frac{1}{|B_{t-1}^u|} \sum_{l \in B_{t-1}^u} p(i \in B_t^u | l \in B_{t-1}^u)$$

- $\mathcal{A} \in [0, 1]^{|U| \times |I| \times |I|}$ is a transition tensor.

Problems of personalized ML-Estimation:

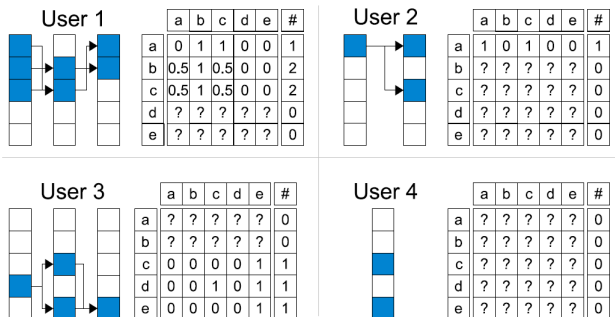
- Many of the parameters cannot be estimated.
- Theoretical properties are easily fail since the data is extremely sparse.

Personalized Markov Chains

- Maximum likelihood estimator for $a_{u,l,i}$ given \mathcal{B} is :

$$\hat{a}_{u,l,i} = \hat{p}(i \in B_t^u | l \in B_{t-1}^u) = \frac{|(B_t^u, B_{t-1}^u) : i \in B_t^u \wedge l \in B_{t-1}^u|}{|(B_t^u, B_{t-1}^u) : l \in B_{t-1}^u|}$$

- Example :



Factorization of the Transition Cube

- $\hat{\mathcal{A}}$ is modeled by the pairwise interactions :

$$\hat{a}_{u,l,i} := \langle v_u^{U,I}, v_i^{I,U} \rangle + \langle v_i^{I,L}, v_l^{L,I} \rangle + \langle v_u^{U,L}, v_l^{L,U} \rangle$$

- or equivalently :

$$\hat{a}_{u,l,i} := \sum_{f=1}^{k_{U,I}} v_{u,f}^{U,I} v_{i,f}^{I,U} + \sum_{f=1}^{k_{I,L}} v_{i,f}^{I,L} v_{l,f}^{L,I} + \sum_{f=1}^{k_{U,L}} v_{u,f}^{U,L} v_{l,f}^{L,U}$$

where $V^{U,I} \in \mathbb{R}^{|U| \times k_{U,I}}$, $V^{I,U} \in \mathbb{R}^{|I| \times k_{U,I}}$, $V^{I,L} \in \mathbb{R}^{|I| \times k_{I,L}}$,
 $V^{L,I} \in \mathbb{R}^{|I| \times k_{I,L}}$, $V^{U,L} \in \mathbb{R}^{|U| \times k_{U,L}}$ and $V^{L,U} \in \mathbb{R}^{|I| \times k_{U,L}}$.

Factorizing Personalized Markov Chains (FPMC)

- In total the FPMC model is:

$$\hat{p}(i \in B_t^u | B_{t-1}^u) = \langle v_u^{U,I}, v_i^{I,U} \rangle + \frac{1}{|B_{t-1}^u|} \sum_{I \in B_{t-1}^u} (\langle v_i^{I,L}, v_i^{L,I} \rangle + \langle v_u^{U,L}, v_i^{L,U} \rangle)$$

- As \mathcal{A} is modelled by a low rank approximation $\hat{\mathcal{A}}$:
 - Parameters are estimated from many data points.

Item Recommendation with FPMC

- Bayesian Personalized Ranking (BPR) [1]
- Assumption : a user prefers an item in basket at a specific time than any other items apart from those in the basket.
- For any item i in basket and any item j not in basket, we need to maximize

$$p(i >_{u,t} j | \Theta) = p(\hat{x}_{u,t,i} >_{\mathbb{R}} \hat{x}_{u,t,j} | \Theta)$$

where $\hat{x}_{u,t,i} = \hat{p}(i \in B_t^u | B_{t-1}^u)$ and Θ are the factorization matrices.

- The objective function can be written as follows :

$$J = - \sum_{u \in U} \sum_{B_t \in \mathcal{B}^u} \sum_{i \in B_t} \sum_{j \notin B_t} \ln \sigma(\hat{x}_{u,t,i} - \hat{x}_{u,t,j}) + \frac{\lambda_{\Theta}}{2} \| \Theta \|_{\mathcal{F}}^2$$

[1] S. Rendle, et al. *Bpr : Bayesian personalized ranking from implicit feedback*. In UAI, 2009.

Expressiveness

- For item recommendation with FPMC, the (U, L) interaction can be dropped. And FPMC can be rewritten as:

$$\hat{x}_{u,t,i}^{FPMC} = \hat{x}_{u,t,i}^{MF} + \hat{x}_{u,t,i}^{FMC}$$

where $\hat{x}_{u,t,i}^{MF}$ is the standard matrix factorization model :

$$\hat{x}_{u,t,i}^{MF} = \langle v_u^{U,I}, v_i^{I,U} \rangle$$

and $\hat{x}_{u,t,i}^{FMC}$ is the non-personalized factorized Markov chain :

$$\hat{x}_{u,t,i}^{FMC} = \frac{1}{|B_{t-1}|} \sum_{I \in B_{t-1}} \langle v_i^{I,L}, v_i^{L,I} \rangle.$$

- Thus FPMC subsumes both the MF and MC models.

Experimental results

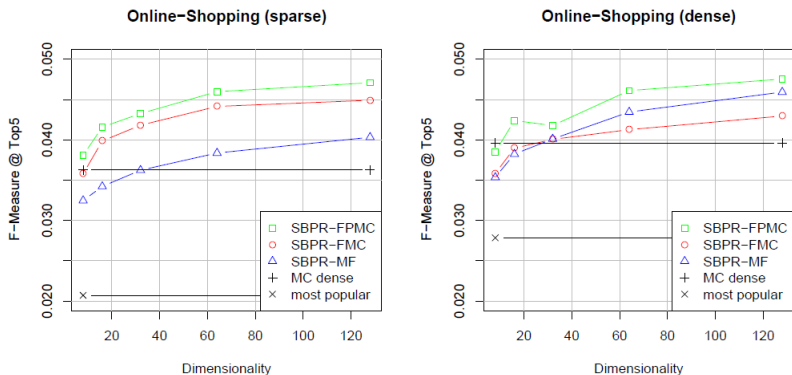


Figure 4: Comparison of FPMC to a factorized Markov chain (FMC), matrix factorization (MF) a standard dense Markov chain (MC dense) learned with Maximum Likelihood and the baseline most-popular.

A Dynamic Recurrent Model for Next Basket Recommendation

International World Wide Web Conference 2010

Feng Yu, et al.

Intuition of DREAM

- MC based methods can only model local sequential behaviors between two adjacent baskets.
 - ⇒ Deep RNN architecture can obtain some global sequential features for all users from historical transaction data.

Problem Formulation

- $N \in \mathbb{R}^{I \times k}$: representations of items.
- $B^u = \{B_{t_1}^u, B_{t_2}^u, \dots\}$
where $B_{t_i}^u$ is a basket of items purchased by user u at time t_i .
- $B_{t_i}^u = \{n_{t_i,j}^u \in \mathbb{R}^k \mid j = 1, \dots, |B_{t_i}^u|\}$
- $n_{t_i,j}^u$: latent representation of the j -th item in B_{t_i}

A Dynamic Recurrent Model (DREAM)

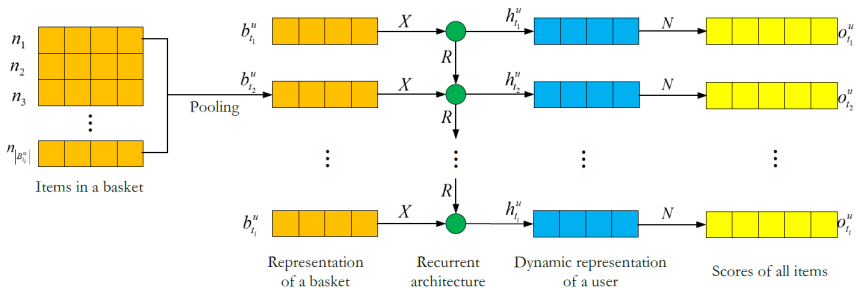


Figure 5: The framework of DREAM.

A Dynamic Recurrent Model (DREAM)

- *Max pooling* operation

$b_{t_i,k}^u$ represents latent basket representation of the user's basket at time t_i :

$$b_{t_i,k}^u = \max(n_{t_i,1,k}^u, n_{t_i,2,k}^u, \dots, n_{t_i,|B_{t_i}^u|,k}^u)$$

where $n_{t_i,j,k}^u$ is the k -th value of $n_{t_i,j}^u$.

A Dynamic Recurrent Model (DREAM)

- Hidden features

$h_{t_i}^u$ is dynamic representation of user u at time t_i :

$$h_{t_i}^u = f(Xb_{t_i}^u + Rh_{t_i-1}^u)$$

where $R \in \mathbb{R}^{k \times k}$ propagates sequential signals between every two adjacent hidden states, $X \in \mathbb{R}^{k \times k}$ is a transition matrix between latent vector representation of baskets and user's interest and f is an activation function (sigmoid).

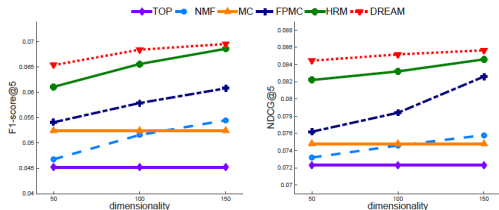
- Output

$o_{t_i}^u \in \mathbb{R}^I$ is scores of all items for user u :

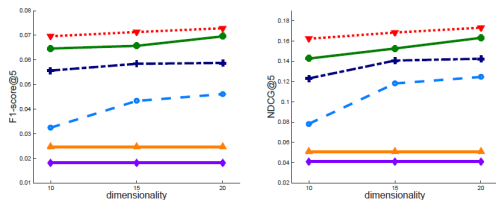
$$o_{t_i}^u = Nh_{t_i}^u$$

where $N \in \mathbb{R}^{I \times k}$ is item matrix.

Experimental results



(a) TaFeng



(b) Tmall

Figure 6: Experiment Results of different methods on two datasets.