

Deep Learning based Recommender System: A Survey and New Perspectives (Autoencoder based Recommendation System)

Shuai zhang, Lina yao and Aixin sun

Presented by Boyoung Kim

November 22, 2017

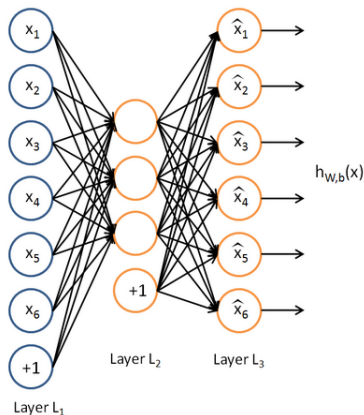
Contents

- 1 Introduction : Auto-encoder
- 2 AutoRec. *Suvash Sedhain, et al.* (ACM, 2015)
- 3 CFN. *Florian Strub, et al.* (DLRS, 2016)
- 4 CDAE. *Yao Wu, et al.* (WSDM, 2016)
- 5 CDL. *Hao Wang, et al.* (SIGKDD, 2015)
- 6 DCF. *Sheng Li, et al.* (CIKM, 2015)

Introduction : Auto-encoder

- Unsupervised learning version of Neural Network.
- AE can be used for dimensionality reduction of high-dimensional data.
- AE generate a hidden representation from an input, and reconstruct the output as the input from the hidden representation.
- Setting the target values to be equal to the input : $h_{W,b}(x) \approx x(\hat{x} \approx x)$.

Introduction : Auto-encoder



- $h_{W,b}(x) = f(W_2 \cdot g(W_1x + b_1) + b_2)$
- Stacked Auto-encoder :
Auto-encoder with more than 1 hidden layer

Figure: Architecture of autoencoder

Contents

- 1 Introduction : Auto-encoder
- 2 AutoRec. *Suvash Sedhain, et al.* (ACM, 2015)**
- 3 CFN. *Florian Strub, et al.* (DLRS, 2016)
- 4 CDAE. *Yao Wu, et al.* (WSDM, 2016)
- 5 CDL. *Hao Wang, et al.* (SIGKDD, 2015)
- 6 DCF. *Sheng Li, et al.* (CIKM, 2015)

AutoRec: Autoencoders Meet Collaborative Filtering

- Suppose we have M users, N items.
- We use **different Autoencoder for each user or each item**.
- Each Autoencoder only has input units for the users who rate that item.
- Every Autoencoder has the same number of hidden units.
- Each autoencoder only has a single training case, but all of the corresponding weights and biases are tied together.

Item-based AutoRec model

- The input, output units model **ratings as real values**.
- Let $r^{(i)}$ denote partial observed vector for item i .

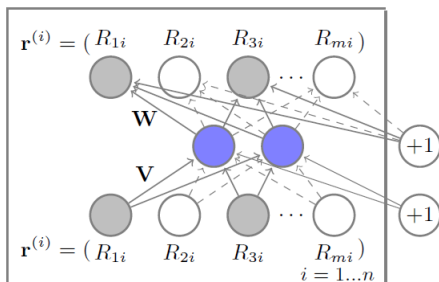


Figure: Item-based AutoRec model

Item-based AutoRec model

- Suppose that the item is rated by n users.
- Then the hidden and output units are :

$$h_j = g\left(\sum_{i=1}^n V_{ij} r_j^{(i)} + a_j\right) \quad \text{and}$$

$$\hat{r}_j^{(i)} = f\left(\sum_k W_{ik} h_k + b_j\right)$$

where $f(\cdot)$ and $g(\cdot)$ are activation functions.

- ✓ Using identity $f(\cdot)$ and sigmoid $g(\cdot)$ functions has good performance.

AutoRec : Learning

- Gradient descent method using "Backpropagation algorithm".
- The objective function for a single training example :

$$\min_{W, V, a, b} \frac{1}{N} \sum_{i=1}^N \| r^{(i)} - \hat{r}^{(i)} \|_{\mathcal{O}}^2 + \lambda \cdot \text{Regularizer}$$

where $\| \cdot \|_{\mathcal{O}}^2$ means that we only consider the contribution of observed ratings.

- ✓ I-AutoRec performs better than U-AutoRec, since the average number of ratings per item is much more than those per user.
- ✓ Stacking more layers improves the performance.

Contents

- 1 Introduction : Auto-encoder
- 2 AutoRec. *Suvash Sedhain, et al.* (ACM, 2015)
- 3 CFN. *Florian Strub, et al.* (DLRS, 2016)**
- 4 CDAE. *Yao Wu, et al.* (WSDM, 2016)
- 5 CDL. *Hao Wang, et al.* (SIGKDD, 2015)
- 6 DCF. *Sheng Li, et al.* (CIKM, 2015)

Collaborative Filtering Neural network(CFN)

- Extension of AutoRec
- **Denoising AutoEncoder**
 - In this paper, masking noise is imposed.
 - $\tilde{r}^{(i)}$ denotes the corrupted input of $r^{(i)}$

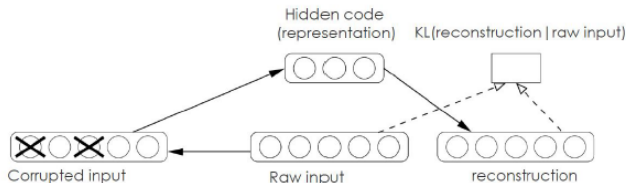


Figure: A denoising AE

Collaborative Filtering Neural network(CFN)

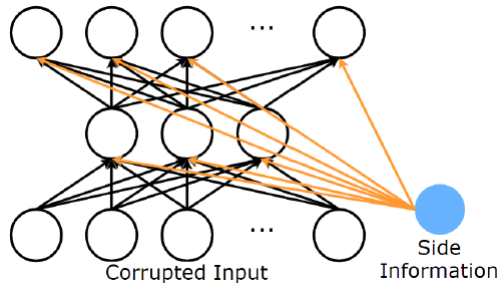
- DAE loss

$$\mathcal{L} = \alpha \left(\sum_{(i,j) \in I(\mathcal{O}) \cap I(\mathcal{C})} [h(\tilde{r}^{(i)})_j - r_j^{(i)}]^2 \right) + \beta \left(\sum_{(i,j) \in I(\mathcal{O}) \setminus I(\mathcal{C})} [h(\tilde{r}^{(i)})_j - r_j^{(i)}]^2 \right) + \lambda \cdot \text{Regularization}$$

- $I(\mathcal{O})$ and $I(\mathcal{C})$ are the indices of observed and corrupted elements
- α and β are two hyper parameters which balance the reconstruction and prediction error

Collaborative Filtering Neural network(CFN)

- Further extension of CFN also incorporates side information in every layer.
- It can be stacked.



$$h(\{\tilde{r}^{(i)}, s_i\}) = f(W_2 \cdot \{g(W_1 \cdot \{\tilde{r}^{(i)}, s_i\} + b_1), s_i\} + b_2)$$

where s_i is side information of item i .

Contents

- 1 Introduction : Auto-encoder
- 2 AutoRec. *Suvash Sedhain, et al.* (ACM, 2015)
- 3 CFN. *Florian Strub, et al.* (DLRS, 2016)
- 4 CDAE. *Yao Wu, et al.* (WSDM, 2016)
- 5 CDL. *Hao Wang, et al.* (SIGKDD, 2015)
- 6 DCF. *Sheng Li, et al.* (CIKM, 2015)

Collaborative Denoising Auto-Encoder(CDAE)

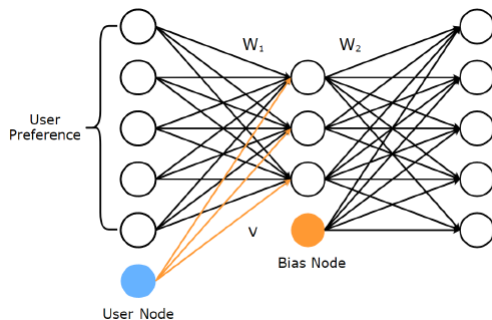
- Implicit feedback dataset
- If the user likes the item, the entry value is 1, otherwise 0.
- Gaussian noise or Mask-out/drop-out noise is used.
- Mask-out/drop-out corruption :

$$P(\tilde{r}_d^{(u)} = \delta r_d^{(u)}) = 1 - q, P(\tilde{r}_d^{(u)} = 0) = q$$

To make the corruption unbiased, one sets $\delta = \frac{1}{1-q}$.

Collaborative Denoising Auto-Encoder(CDAE)

- $\mathbf{V}_u \in \mathbb{R}^k$: weight vector for the user input node where k is the number of hidden units. Note that \mathbf{V}_u is a user-specific vector.



$$h(\tilde{r}^{(u)}) = f(W_2 \cdot g(W_1 \cdot \tilde{r}^{(u)} + V_u + b_1) + b_2)$$

Collaborative Denoising Auto-Encoder(CDAE)

- Parameters are learned by

$$\operatorname{argmin}_{W_1, W_2, V, b_1, b_2} \frac{1}{M} \sum_{u=1}^M \mathbb{E}_{p(\tilde{r}^{(u)} | r^{(u)})} [l(\tilde{r}^{(u)}, h(\tilde{r}^{(u)}))] + \lambda \cdot \text{Regularization}$$

The loss function $l(\cdot)$ can be square loss or logistic loss.

- Negative sampling : Sampling small subset from negative set and user's preferences of items are used for computing gradients reduces the time complexity.

Contents

- 1 Introduction : Auto-encoder
- 2 AutoRec. *Suvash Sedhain, et al.* (ACM, 2015)
- 3 CFN. *Florian Strub, et al.* (DLRS, 2016)
- 4 CDAE. *Yao Wu, et al.* (WSDM, 2016)
- 5 CDL. *Hao Wang, et al.* (SIGKDD, 2015)**
- 6 DCF. *Sheng Li, et al.* (CIKM, 2015)

Collaborative Deep Learning(CDL)

- Hierarchical Bayesian model which integrates SDAE and MF
- Modeling the noise to get robust result.
- Implicit feedback dataset
- Notation
 - X_c : $N \times S$ item content matrix (clean output)
 - X_{c,j^*} : item j 's content. j -th row of X_c
 - X_0 : corrupted input
 - X_l : $N \times D_l$ the output of layer l of the SDAE.
 - L : number of layers

Generative process of CDL

- For each layer l of the SDAE network,
 - $W_{l,*n} \sim \mathcal{N}(0, \lambda_w^{-1} I_{D_l})$
 - $b_l \sim \mathcal{N}(0, \lambda_w^{-1} I_{D_l})$
 - For each row j of X_l , $X_{l,j*} \sim \mathcal{N}(\sigma(X_{l-1,j*} \cdot W_l + b_l), \lambda_s^{-1} I_{D_l})$
- For each item j ,
 - Draw a clean input $X_{c,j*} \sim \mathcal{N}(X_{L,j*}, \lambda_n^{-1} I_s)$
 - Draw a latent item offset vector $\epsilon_j \sim \mathcal{N}(0, \lambda_v^{-1} I_K)$, and set the latent item vector:

$$v_j = X_{\frac{L}{2},j*}^T + \epsilon_j$$

- Draw a latent user vector for each user i : $u_i \sim \mathcal{N}(0, \lambda_u^{-1} I_K)$.
- Draw a rating R_{ij} for each user-item pair (i, j) :

$$R_{ij} \sim \mathcal{N}(u_i^T v_j, C_{ij}^{-1})$$

where C_{ij} is a confidence parameter $C_{ij} = a$ if $R_{ij} = 1$, $C_{ij} = b$ o.w. ($a > b > 0$)

Collaborative Deep Learning(CDL)

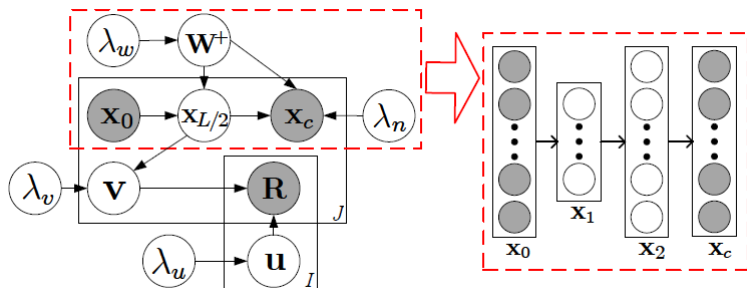


Figure: Graphical model of CDL when λ_s approaches positive infinity

Collaborative Deep Learning(CDL)

- Maximizing a posterior probability is equivalent to maximizing the joint log-likelihood of parameters.

$$\begin{aligned}
 \mathcal{L} = & -\frac{\lambda_u}{2} \sum_i \|u_i\|_2^2 - \frac{\lambda_w}{2} \sum_l (\|W_l\|_F^2 + \|b_l\|_2^2) \\
 & - \frac{\lambda_v}{2} \sum_j \|v_j - X_{\frac{l}{2}, j^*}^T\|_2^2 - \frac{\lambda_n}{2} \sum_j \|X_{L, j^*} - X_{C, j^*}\|_2^2 \\
 & - \frac{\lambda_s}{2} \sum_{l, j} \|\sigma(X_{l-1, j^*} W_l + b_l) - X_{l, j^*}\|_2^2 \\
 & - \sum_{i, j} \frac{C_{ij}}{2} (R_{ij} - u_i^T v_j)^2
 \end{aligned}$$

Contents

- 1 Introduction : Auto-encoder
- 2 AutoRec. *Suvash Sedhain, et al.* (ACM, 2015)
- 3 CFN. *Florian Strub, et al.* (DLRS, 2016)
- 4 CDAE. *Yao Wu, et al.* (WSDM, 2016)
- 5 CDL. *Hao Wang, et al.* (SIGKDD, 2015)
- 6 DCF. *Sheng Li, et al.* (CIKM, 2015)**

Deep Collaborative Filtering Framework(DCF)

- DCF unifies the deep learning models with MF which makes use of both rating matrix and side information.
- Let X and Y denote side information of user and item.
- The objective function of mDA-CF is

$$\operatorname{argmin}_{U, V, W_1, W_2} I(R, U, V) + \beta(\|U\|_F^2 + \|V\|_F^2) + \gamma\mathcal{L}(X, U) + \delta\mathcal{L}(Y, V)$$

where β, γ, δ are the trade-off parameters.

- In particular, the latent factors are extracted from the hidden layer of deep networks.

Deep Collaborative Filtering Framework(DCF)

