

# Generative Auto Encoder

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# 1 Introduction

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# Introduction

- Estimation of deep generative models have received much attentions.
- There are two popular approaches, one is called variational auto encoder (VAE, Kingma and Welling (2013)) and the other is called generative adversarial networks (GAN, Goodfellow et al. (2014)).
- Based on the auto encoder, we propose a simple and novel approach to generative model.

## Basic structure of deep generative model

- In many studies of deep generative model, the marginal distribution of observation  $x$  is assumed to be a mixture of latent variables  $z$  given as:

$$P(x; \theta) = \int_z P(x|z; \theta)P(z)dz$$

where  $P(\cdot|z; \theta)$  is a decoder parametrized by  $\theta$ .

- They model the marginal distribution of latent variable  $z$ ,  $P(z)$ , to normal or uniform distribution.
- In this assumption, it requires many calculations to transform latent variable into real data, thus decoder and encoder have to be deep structures.

## Our contributions

- We propose a simple but efficient algorithm to estimate the generate model for given data based on the auto-encoder, which is called generative auto encoder (GAE).
- Especially, we do not design specific form of the marginal distribution of latent variable, for instance  $\mathcal{N}(0, I)$ , and let the distribution be **determined by complexity of networks and input data**.
- By doing this, we expect that our method achieve similar or superior performance **with more compact structure** than other generative methods.

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## Model description

- We model the marginal distribution of latent variable  $z$  to **mixture of train data** as follows:

$$\begin{aligned}P(z; \phi) &= \int_{\mathcal{Y}} P(z|y; \phi) d\hat{F}(y) \\ &= \frac{1}{n} \sum_{j=1}^n P(z|x_j; \phi)\end{aligned}$$

where  $P(\cdot|y; \phi)$  is a encoder parametrized by  $\phi$  and  $\{x_j\}_{j=1}^n$  is train data.

- Here,  $P(\cdot|y; \phi)$  is designed to a multivariate normal distribution, that is, if  $z \sim P(\cdot|y; \phi)$  then

$$z = \mu(y; \phi) + \sigma(y; \phi) \odot \epsilon, \quad \epsilon \sim \mathcal{N}(0, I)$$

where  $\mu(y; \phi)$  and  $\sigma(y; \phi)$  are deep architectures based on NN.



## Model description

- Then the marginal distribution of an observation  $x$  can be rewritten to the following:

$$P(x; \theta, \phi) = \frac{1}{n} \sum_{j=1}^n \int_z P(x|z; \theta) P(z|x_j; \phi) dz$$

- We estimate parameters  $\theta$  and  $\phi$  by maximizing the log likelihood function:

$$\sum_{i=1}^n \log \left[ \frac{1}{n} \sum_{j=1}^n \int_z P(x_i|z; \theta) P(z|x_j; \phi) dz \right]$$

# Regularization

- To avoid over-fitting, we give some regularization terms for  $\mu(\cdot; \phi)$  and  $\sigma(\cdot; \phi)$  as follows:

$$R(x, \phi, \lambda_1, \lambda_2) = \lambda_1 \sum_{j=1}^J \{\mu(x; \phi)_j^2\} \\ + \lambda_2 \sum_{j=1}^J \{1 + \log \sigma(x; \phi)_j^2 - \sigma(x; \phi)_j^2\}$$

where  $\lambda_1, \lambda_2 > 0$  are hyperparameters and  $J$  is dimension of the latent space.

- The above regularization term is motivated by the regularization term of VAE.
- Then the final objective function is given as:

$$\sum_{i=1}^n \log \left[ \frac{1}{n} \sum_{j=1}^n \int_z P(x_i | z; \theta) P(z | x_j; \phi) dz \right] + \sum_{i=1}^n R(x_i, \phi, \lambda_1, \lambda_2)$$

## Generation of samples

- Our proposed method has slightly different procedure to generate samples because we also model  $P(z)$  to a mixture of train data.
- The procedure to generate samples is as follows:
  - 1 Sample  $y$  from  $\hat{P}$  where  $\hat{P}$  is empirical distribution.
  - 2 Given  $y$ , sample  $z$  from  $P(\cdot|y; \phi)$ .
  - 3 Given  $z$ , sample  $x$  from  $P(\cdot|z; \theta)$ , which a generated sample using our method.

## Estimation of parameters

- Note that we can rewrite the log likelihood function as follows:

$$\sum_{i=1}^n \log \left[ \int_y \int_z P(x_i|z; \theta) dF(z|x_j; \phi) d\hat{F}(y) \right]$$

- It is infeasible to calculate  $P(x; \theta, \phi)$ , while  $P(x, z, y; \theta, \phi)$  is easy to calculate which is given as

$$P(x, z, y; \theta, \phi) = \hat{P}(y) \cdot P(z|y; \phi) \cdot P(x|z; \theta).$$

- So we treat  $y$  as well as  $z$  as latent variables and optimize the log likelihood using EM algorithm.

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# Experiments

- We conduct 3 numerical experiments comparing our method with other methods on multiple benchmark datasets.
  - 1 First, we generate samples to confirm whether our method generate visually realistic and diverse images.
  - 2 Secondly we visualize the marginal distribution of latent variable  $z$ . We expect that the more simple the architectures are the more complex the marginal distribution of  $z$  is.
  - 3 Lastly we conduct quantitative analysis to measure the performance of our method. Two measures are used, KDE and approximated log likelihood.

# Generated images

## MNIST dataset



**Figure :** (Left) Generated samples using our method (Right) Generated samples using VAE. All samples are generated randomly. It seems that our method consistently generates visually realistic images.

# Generated images

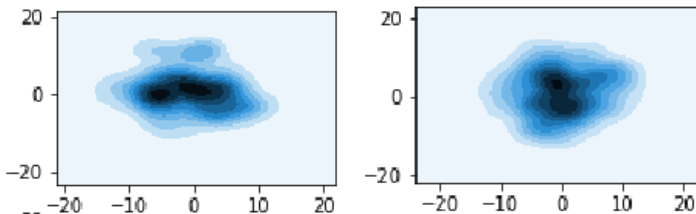
## Toronto Face Dataset (TFD)

- We forgot to save the best model...



# Visualization of latent space

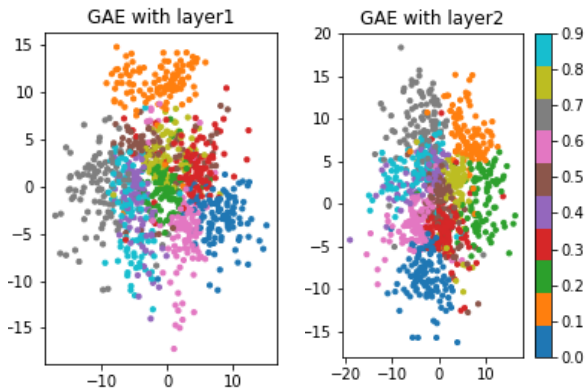
## MNIST dataset



**Figure :** We sample 1000 samples of latent variable and conduct kernel density estimation using these samples. We use 2-dimensional latent space. **(Left)** Estimated kernel density with 1-layered dec. and enc. **(Right)** Estimated kernel density with 2-layered dec. and enc.

# Visualization of latent space

## MNIST dataset



**Figure :** Using test dataset, we sample  $z$  from  $P(\cdot|x; \phi)$  and plot these  $z$ s.  $z$ s are colored according to their true class label. **(Left)** Scatter plot with 1-layered dec. and enc. **(Right)** Scatter plot with 2-layered dec. and enc.

# Quantitative analysis

## Kernel density estimation (KDE)

- We generate 10,000 samples and conduct kernel density estimation using these samples.
- Then we calculate test log likelihood of test data using the estimated kernel density.

Method	MNIST	TFD
VAE(Kingma and Welling, 2013)	296.77	2572.59
GAN(Goodfellow et al., 2014)	300.331	2057
GMMN+AE(Li et al., 2015)	282	2294
AAE(Makhzani et al., 2015)	340	2252
GAE(1 layered)	<b>456.71</b>	<b>2815.76</b>
GAE(2 layered)	<b>460.73</b>	<b>2796.91</b>

**Table :** Test performances on MNIST and TFD datasets.

## Quantitative analysis

### Approximated log likelihood

- Approximate test log likelihood by sampling latent variable  $z$  as follows:

$$\log P(x) \approx \log \left[ \frac{1}{S} \sum_{s=1}^S P(x|z_s; \theta) \right], \quad z_s \sim P(z)$$

Method	biMNIST
VAE(1 layered)(Kingma and Welling, 2013)	-107.18
VAE(2 layered)	-96.94
VAE(3 layered)	-97.62
VAE(4 layered)	-102.97
GAE(1 layered)	<b>-97.66</b>
GAE(2 layered)	<b>-96.91</b>
GAE(3 layered)	<b>-95.76</b>
GAE(4 layered)	<b>-94.66</b>

Table : Test performances on biMNIST dataset.

## References

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