

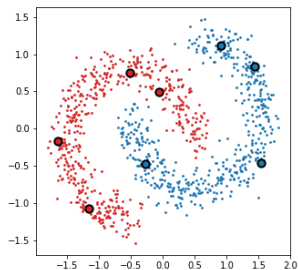
Semi-supervised learning with MixUp method - ICT

YC, Choi

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Semi-supervised learning

- ▶ Semi-supervised learning : Leveraging large amounts of unlabeled data to improve the performance of supervised learning.
- ▶ Cluster assumption : if two samples belong to the same cluster in the input distribution, then they are likely to belong to the same class.
- ▶ low-density separation assumption : the decision boundary should lie in the low-density regions.



Consistency-Regularization approach

- ▶ encouraging invariant prediction $f(u) = f(u + \delta)$ for perturbations $u + \delta$ of unlabeled data u .
- ▶ There are many consistency-regularization techniques depending on how to choose δ .
- ▶ Random perturbation, data augmentation are kind of Consistency-Regularization methods.

Virtual adversarial training(VAT)(2018)

- ▶ VAT(Miyato et al., 2018) searches for small perturbation δ that maximize the change in the prediction of the model.
- ▶ $r_{\text{advr}}(\mathbf{u}, c) = \operatorname{argmax}_{r; \|r\| \leq c} D_{\text{KL}} \left(p(\cdot | \mathbf{u}; \hat{\theta}) || p(\cdot | \mathbf{u} + r; \hat{\theta}) \right)$

Bad-GAN(2017)

- ▶ Bad-GAN uses a complement generator which generates complements samples in the feature space.
- ▶ For K classification problem, we give $K+1$ label to complements samples.
- ▶ Under mild assumptions, optimal discriminator learns correct decision boundary.
- ▶ The discriminator obtains class boundaries in low-density area. (cluster assumption)

Fast adversarial training(FAT)

- ▶ Idea : Generating complements samples without GAN would be computationally efficient.
- ▶ The perturbation(r_{adv}) of VAT is toward decision boundary.
- ▶ The region of decision boundary would be expected to low-density.
- ▶ We give larger value Cr_{adv} and $x + Cr_{adv}$ is considered complement sample. $C > 0$

Interpolation Consistency Training(ICT)(2019)

- ▶ Consistency-Regularization method.
- ▶ Encouraging consistent predictions $f(\alpha u_1 + (1 - \alpha)u_2) = \alpha f(u_1) + (1 - \alpha)f(u_2)$
- ▶ Let $\text{Mix}_\lambda(u_j, u_k) = \lambda u_j + (1 - \lambda)u_k$
- ▶ Most of $\text{Mix}_\lambda(u_j, u_k)$ lie on regions of low density.
- ▶ The entropy of $\text{Mix}_\lambda(f_{\theta'}(u_j), f_{\theta'}(u_k))$ may
- ▶ So, ICT uses unlabeled loss : $L(\theta) = \|\mathbf{f}_\theta(\text{Mix}_\lambda(u_j, u_k)) - \text{Mix}_\lambda(\mathbf{f}_{\theta'}(u_j), \mathbf{f}_{\theta'}(u_k))\|_2$

MixMatch(2019)

- ▶ Consistency-Regularization method
- ▶ The differences between ICT and MixMatch are
 1. Label Guessing
 2. Sharpening
 3. Using Labeled data to make mixup loss.

MixMatch(2019)

- ▶ Label Geussing : $\bar{q}_b = \frac{1}{K} \sum_{k=1}^K P_{\text{model}}(y|\hat{u}_{b,k}; \theta)$
where $\hat{u}_{b,k}$ is a k-th augmented data from u_b
- ▶ Sharpen(p, T)_i := $p_i^{1/T} / \sum_{j=1}^L p_j^{1/T}$
Using sharpening technique, $q_b = \text{Sharpen}(\bar{q}_b, T)$ is considered as target for the model's prediction.



MixMatch(2019)

- ▶ Let $\hat{\mathcal{X}} = ((\hat{x}^b, p_b) : b \in (1, \dots, B))$ and
 $\hat{\mathcal{U}} = ((\hat{u}_{b,k}, q_b) : b \in (1, \dots, B), k \in (1, \dots, K))$

- ▶ The new generated datasets are

$$\mathcal{X}'_i = \text{Mix}_{\lambda}(\hat{\mathcal{X}}_i, \text{shuffle}(\text{Concat}(\hat{\mathcal{X}}, \hat{\mathcal{U}}))_i)$$

$$\mathcal{U}'_i = \text{Mix}_{\lambda}(\hat{\mathcal{U}}_i, \text{shuffle}(\text{Concat}(\hat{\mathcal{X}}, \hat{\mathcal{U}}))_{i+|\hat{\mathcal{X}}|})$$

- ▶ The final loss are...

$$\mathcal{L}_{\mathcal{X}} = \frac{1}{|\mathcal{X}'|} \sum_{x, p \in \mathcal{X}'} H(p, p_{\text{model}}(y|x; \theta))$$

$$\mathcal{L}_{\mathcal{U}} = \frac{1}{|\mathcal{U}'|} \sum_{u, q \in \mathcal{U}'} \|q - p_{\text{model}}(y|u; \theta)\|_2^2$$

Experiments

- ▶ Dataset : CIFAR-10(4000 labels)
- ▶ Preprocessing : zero-pad each image with 2 pixels, random crop, horizontal flip w/ prob 0.5 followed by per-channel standardization and ZCA.
- ▶ Architecture : CNN-13, Wide-Resnet-28-2.

Experiments-result

Method Model	Test acc.(%)	
	CNN-13	WRN28-2
CrossEnt(SL)	50.30	-
VAT	84.19	-
FAT	85.13	-
ICT	92.08	92.11
VAT + ICT	91.39	92.02
FAT + ICT	91.78	92.30
MixMatch	-	95.05 [†]

Table 1: Comparison of prediction accuracies. † refers to the result reported in the paper. The red text refers to under training

Implementation details

- ▶ I run the experiments for 450 epochs.
- ▶ The initial learning rate was set to 0.1
- ▶ The momentum was set to 0.9, L2 regularization coefficient 0.0001 and a batch-size of 100.
- ▶ The Consistency coefficient is ramped up from its initial value 0.0 to its maximum value at one-fourth of the total number of epochs using the same sigmoid schedule of (Tarvainen and Valpola, 2017)
- ▶ The maximum value of consistency coefficient is set to 100.